BALLIN et al
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AMENDMENTS TO THE ABSTRACT:

Please amend the Abstract as shown on a separate page attached hereto.



A hierarchical behavioural behavioral framework is used to generate and control autonomous and semi-autonomous behaviour-behavior in an articulate object. A behavioural behavioural controller is arranged to receive input associated with a behavioural-behavioral action, to infer a plurality of behavioural behavioral parameter values using the framework, and to generate equivalent behaviour behavior in the articulate object using the parameter values when loaded in the behavioural-behavioral controller to generate output corresponding to the equivalent behaviour behavior may reproduce the inputted behavioural behavioral action, and /or comprise include one or more other behavioural behavioural behavioural setions, which may be performed simultaneously or as part of a sequence of actions.